DESIGN OF SINGLE SAMPLING PLAN BY DISCRIMINANT AT MAPD

T.B.Ramkumar

Department of Statistics, St. Thomas College Thrissur - 680 001, India. e-mail: rktmidhuna@qmail.com

Paper received on 23 June 2009; revised, 31 July 2009; accepted, 30 August 2009.

Abstract. This paper presents a procedure for designing a single sampling plan indexed through maximum allowable proportion defective (MAPD) along with Tangential distance (Discriminant). It is discussed how the declination angle of the tangent at the inflection point of the OC curve discriminates the SSP. Tables are presented for the selection of plans based on MAPD with Discriminant or declination angle of the tangent. Also an optimum sampling plan is introduced for an Operating Ratio of MAPD to Discriminant and the uses were studied.

Keywords Single Sampling Plan, Maximum Allowable Proportional Defective, Tangent intercept, Inflection point, Operating Characteristic curve, Discriminant, Operating Ratio and Declination angle. Optimum Sampling Plan.

1 Introduction

MAPD is a key measure assessing to what degree the inflection point empowers the OC curve to discriminate between good and bad lots. Mayor [3] introduced the concept of MAPD in a SSP using Poisson model. MAPD locates a point of the OC curve at which the descent is steepest. It is defined as the proportion of defective beyond which consumer won't be willing to accept the lot. Mandelson [2] has explained the desirability for developing a system of sampling plan indexed by MAPD and suggested a relation $p^* = c/n$. Soundararajan [5] has indexed SSP through MAPD and $K(p_T/p^*)$. Muthuraj and Soundararajan [4]has studied the selection of single sampling plan indexed by p^* with its relative slope. Norman Bush [1]developed a SSP based on tangent at inflection point. This technique states that a straight line will uniquely portray the slope of OC curve and hence the OC is fixed. According to Norman Bush the point of inflection has been chosen because it is most representative point of an OC curve showing the turning point of quality since the maximum tangent occurs at this point. Ramkumar [6] has developed a selection procedure for

SSP involving AQL and tangent intercept in the p axis. Ramkumar [7] developed a set of sampling plans indexed through MAAOQ, MAPD explaining the adequacy of MAPD as quality.

A tangent is drawn at the inflection point of an OC curve, where p_T is the tangent intercept to the p-axis and $L(p_T)$ is the tangent intercept to the L(p)-axis. Define Discriminant \mathbf{D} as the distance in the L(p) coordinate of the inflection point, from $L(p^*)$ to the point $L(p_T)$, i.e. $D = L(p_T) - L(p^*)$. When \mathbf{D} is large there is a high degree of discrimination power and when D is small the discrimination decreases (From Figure 1). The Discriminant \mathbf{D} is a function of c alone (Equation: 6) and it is monotonically increasing with respect to c (Table 1). Therefore there exists an acceptance number c corresponding to each value of D i.e. there is a unique sampling plan for each D. The slope of the OC curve is horizontal at the inflection point and a sharp decline in the probability of acceptance is expected for the proportion of defective beyond p^* . The declination angle A of the tangent also represents the discrimination power of the OC curve. When A decreases OC curve becomes more stringent. From the relation Tan $A = p^*/\mathbf{D}$ one can find (n, c) for a given p^* and D. Thus it is seen that both A and \mathbf{D} uniquely determines the SSP.

2 Selection of sampling plans

D is given for twenty values of $c \ge 1$ in Table 1. For a given value of **D** the value of c can be easily read off from the Table 1 (to the next higher value of **D**). SSP with c = 0 are not considered, since c = 0 plans do not have an inflection point on the OC curve.

1) For a specified **D** and p^*

D is a monotonic increasing function of c, there exists a unique c for a given **D** and then $n = c/p^*$, where given **D** is fixed nearer to the next defined **D**. Table 1 gives the value of $L(p_T)$, $L(p^*)$ and **D** for c = 1, 2, ..., 20.

Example 2.1 A manufacturer of plastic products fixes the maximum allowable proportion defectives at 13% and Discriminant of the OC curve $\mathbf{D} = 1.185$.

From Table 1, for a given value of $\mathbf{D} = 1.185$ (> 1.1167 and < 1.1858), c = 8 and n = 61.54 = 62.

Also the angle of declination for (62, 8) Tan A = 0.1097 and A = 6.28°. (This can be easily found from Table 3)

2) For a specified angle A and p^*

Find **D** from the relation $\mathbf{D} = p^*/\tan A$. Then it is easy to fix the corresponding c and hence n using Table 1. It is clear that **D** is inversely proportional to angle A for fixed p^* , implies that more efficient OC curves can be developed based on angle A.

Example 2.2 A company claims that the OC curve for their electrical switches has MAPD= 5% and angle of declination of tangent at MAPD is $5\degree$, $\mathbf{D} = p^*/\tan A$ i.e. $\mathbf{D} = 0.05/0.0875 = 0.5714$

From Table: 1, for $\mathbf{D} = 0.5714$ (> 0.5413 with c = 2) and $p^* = 0.05$, the sampling plan is (40, 2).

3) For a specified \mathbf{D} and A

Table 3 are constructed to find suitable sampling plans when **D** and A are specified. Trace the angle A (numerically exceeding) in Table 3 and find out the corresponding p^* at A for given **D**. Correspondingly (n, c) is obtained.

Example 2.3 In an OC curve to which a tangent is drawn through the inflection point has $\mathbf{D} = 0.8773$ and declination angle $A = 8^{\circ}$.

Since $\tan A = p^*/D \ p^* = D \ Tan \ A, \ i.e. \ p^* = 0.12$

From the table 3 n = 42 and c = 5.

Then the value of AQL and LTPD for the SSP (42, 5) can be determined using conversion table, see Ramkumar [6] Thus $p_1 = 0.0622$ and $p_2 = 0.2208$, i.e. there is a variation of 6% to 22% in AQL-LTPD values.

Consider the sampling plans, where AQL is fixed:

If $p_1 = 0.0622$ and $p_2 = 0.25$, the corresponding SSP will be (32, 4).

If $p_1 = 0.0622$ and $p_2 = 0.20$, the corresponding SSP will be (53, 6)

OC curves for the SSP (42, 5), (32, 4) and (53, 6) are given in Figure 2.

Comparing the OC curves it is seen that for lesser LTPD value than that obtained from tangential angle plan the better quality products are rejected. For greater LTPD values, unwanted products will be accepted. Implying that tangential angle plan is more efficient for distinguishing good and bad items reasonably at acceptable proportion defective. Discriminant can be defined as a cost function and appropriate sampling plan can be designed for given MAPD. Practically **D** is equated to the cost and OC curve is fixed at the requirement by finding suitable MAPD.

Practically **D** can be defined as a cost function of a unit and then corresponding sampling plans are evaluated. As the cost increases an effective OC curve can be explained.

Theorem 2.1 The discriminant D is independent of sample size n.

By definition the discriminant **D** is the distance from the ordinate of the inflection point $(L(p^*))$ to the tangent intercept $(L(p_T))$ in the L(p) axis. We have

$$\mathbf{D} = L(p_T) - L(p^*) = \frac{e^{-c}c^{c+1}}{c!},$$

which is a function of c alone (see Figure 3).

Implies that **D** is independent of sample size n and there exist a unique constant value of **D** for each c.

3 Construction of tables

The probability of acceptance of a lot with quality p is given by the Poisson model

$$L(p) := e^{-np} \sum_{r=0}^{c} \frac{(n \cdot p)^r}{r!}$$
 (3.1)

where p is the proportion defective of the lot, p coordinate of the inflection point will be obtained as

$$p^* = c/n \tag{3.2}$$

The tangent intercept at p-axis is given by

$$PT := \frac{c}{n} + \frac{c!}{c^c \cdot n} \sum_{r=0}^{c} \frac{c^r}{r!}$$
 (3.3)

Therefore the tangent intercept at L(p)-axis, $L(p_T)$ is given as

$$L(PT) := \frac{e^{-c}c^{c+1}}{c!} + e^{-c} \cdot \sum_{r=0}^{c} \frac{c^r}{r!}$$
(3.4)

 $L(p^*)$ represents the probability of acceptance of an utmost satisfactory quality (MAPD)

$$L(p^*) = e^{-c} \cdot \sum_{r=0}^{c} \frac{c^r}{r!}$$
 (3.5)

Then the Discriminant $\mathbf{D} = L(p_T) - L(p^*)$.

$$\mathbf{D} = \frac{e^{-c} \cdot c^{c+1}}{c!} \tag{3.6}$$

Thus **D** is a function of c alone, and it is constant for fixed c (see Figure 3). From Figure 1

$$\tan A = p^*/\mathbf{D} \tag{3.7}$$

The declination angle

$$A = \tan^{-1}(p^*/\mathbf{D}) \tag{3.8}$$

$$D/np^* = \frac{e^{-c}c^c}{c!} \tag{3.9}$$

For different values of c = 1, 2, ..., 20, **D** is determined from equation (3.6). $L(p^*)$ and $L(p_T)$ can also be found for different c from equation (3.4) and (3.5). Prefixing c and hence **D**, n is determined. Finding c from **D** and substituting c and p^* in equation (3.9), n is determined. Similarly substituting p^* for fixed **D** in equation (3.8) angle A can be determined.

4 Optimum Sampling Plan

For various values of MAPD and Discriminant, there exist a set of sampling plans suitable for defined qualities. But there exist a unique sampling plan with maximum efficiency of the OC curve. Such OC curve having minimum c and maximum discriminatory power develops a sampling plan and it is called Optimum sampling plan. Thus for a particular value of Operating Ratio = MAPD/ Discriminant (which will be ultimately Tan A), a collection of sampling plans can be developed in a specific range of sample size. The first intersection of the value of Operating Ratio in the stream of sampling plans will be the optimum sampling plan with the stringent OC having minimum c among the others. Such a sampling plan contains better quality accepted comparing with all other plans with the defined OR.

Example 4.1 A company fix a primary quality index on OR = .0833 and it is planned to use sampling plans with utmost stringency at the initial lots and eager to switch on to successive levels on continuous acceptance. What will be the minimal security plan and maximum security plan?

Fixing OR at a constant with an admissible range of sampling inspection n = 50to100 from the fig 4(a) possible sampling plans are: (54, 3) (62, 4) (69, 5) (75, 6) (81, 7) (86, 8) (92, 9) and (96, 10).

In these sampling plans the optimum sampling plans are (54, 3) and (96, 10). First intersection (54, 3) is stringent and last intersection (96, 10) is producer friendly.

5 Significance of optimum plan

For regularly consumable homely products with moderate quality like electrical goods, utensils, plastic goods, etc. the quality can be defined in terms of MAPD. But prefixing a quality level at the elementary stage of production is difficult. In these occasions one can begin the production on an Operating Ratio like MAPD/D which entertains both consumer's condition on quality and producer's risk in terms of sharpness of the OC curve. Also it estimates sample size from the range of sample that can be accommodated by the producer for inspection and making use of all these elements a sampling plan is prepared. So one can confidently produce the items in the beginning stages with such a sampling plan and the consumers can propose further refinement on MAPD or sharpness or sample size. The switching rules can be implemented at successive stages of inspection according to the requirement.

6 Figures and Tables

Figure 1 depicts the Discriminant \mathbf{D} , declination angle A for SSP (50, 2) where $P_a(p)$ represents the OC curve, L1(p) represents the tangent and $\mathbf{D} = L(p_T) - L(p^*)$.

Figure 2 show the efficiency of tangential angle plan for attaining most appropriate OC curve.

Figure 3 shows that the discriminant is unaffected by sample number and it is a constant for fixed c. Also, it shows that the OC curve is more stringent when $\tan A$, the inflection tangential angle decreases. Also it ascertains that \mathbf{D} is a constant for fixed c.

Figure 4(a) represent the OR (tan A) for distinct values of c for the range of n varying from 50–100, from which the possible sampling plans for the specified value of OR can be detected. Similarly one can draw OR for different ranges of n. Figure 4(b) ranges n over 100 to 250 and Figure 4(c) over 250 to 500. Figure 5 is the comparison of OC curves indicating the discriminating power of the OC curve. It is used to establish that the Optimum Sampling Plan is determined as one with minimum c or with maximum c as the case is required. Table 1 shows the Discriminant (using (3.6)) and acceptance number can be identified either specifying \mathbf{D} or $L(p^*)$ or $L(p_T)$ for $c=1,2,\ldots,20$.

Table 2 shows the sampling plans for different values of MAPD and Discriminant \mathbf{D} .

Table 3 shows the sampling plans for different values of MAPD and Discriminant **D** and Tangential Angle A, provided any two of them are available.

For Figure 2

Pa(p)	c	n	p^*	D	$\tan A$
$P_{1a}(p)$	5	42	0.119048	0.877337	0.135692
$P_{2a}(p)$	4	32	0.125	0.781467	0.159956
$P_{3a}(p)$	6	53	0.113208	0.963739	0.117467

From Figure 2 the OC Curve is more reasonable with parameters \mathbf{D} and A compared to AQL and LTPD.

For Figure 3, c = 2, n = 50,100 thus $p^* = .04$ and .02 respectively. The inflection tangent meets at 1.218 and $Pa(p^*) = 0.677$ so that D = 0.541.

7 Switching Rule.

For a fixed OR, find plausible sampling plans within a fixed range.

These plausible sampling plans will lead to a switching rule.

Start with moderate (n, c), fixing at middle falling OC curve.

Continue the inspection till k lots are inspected (k depends on the requirement of quality).

Table 1: The Discriminant, y-intercept of MAPD & Tangent intercept for $c=1,2,\ldots,20$

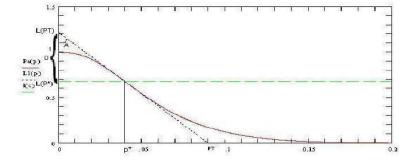
c	D	\mathbf{D}/np^*	$L(P^*)$	$L(P_T)$	c	D	\mathbf{D}/np^*	$L(P^*)$	$L(P_T)$
1	0.3679	0.368	0.7358	1.1037	11	1.3132	0.119	0.5793	1.8925
2	0.5413	0.271	0.6767	1.218	12	1.3724	0.114	0.5759	1.9483
3	0.6721	0.224	0.6472	1.3193	13	1.4292	0.110	0.5731	2.0023
4	0.7815	0.195	0.6289	1.4104	14	1.4838	0.106	0.5704	2.0542
5	0.8773	0.175	0.6159	1.4932	15	1.5365	0.102	0.5681	2.1046
6	0.9637	0.161	0.6063	1.57	16	1.5875	0.099	0.5659	2.1534
7	1.0430	0.149	0.5987	1.6417	17	1.6368	0.096	0.5640	2.2008
8	1.1167	0.140	0.5926	1.7093	18	1.6848	0.094	0.5623	2.2471
9	1.1858	0.132	0.5874	1.7732	19	1.7315	0.091	0.5606	2.2921
10	1.2511	0.125	0.5830	1.8341	20	1.7767	0.089	0.5591	2.3358

Table 2: Certain SSP for given Discriminant **D** and MAPD .10 .12 .20 $p^* : -$.05.08 .14 .15 .18 \mathbf{D} nnnnn0.3679 0.54130.6721 0.78150.87730.96371.0430 1.1167 1.18581.2511 1.3132 1.37241.42921.48381.53651.58751.6368 1.6848 1.73151.7767

Table 3: Certain SSP for given \mathbf{D} and angle A

	Table 3: Certain SSP for given \mathbf{D} and angle A									
c	D P*:-	.01	.05	.08	.11	.13	.15	.20		
1	0.3679	A = 1.55699	7.7395	12.2680	15.2064	16.6464	19.4612	22.1817	28.5297	
		n=100	20	13	10	9	8	7	5	
2	0.5413	1.0584	5.2775	8.4070	10.4668	11.4869	13.5045	15.4886	20.2783	
		200	40	25	18	15	13	10		
3	0.6721	.8524	4.2546	6.78797	8.4628	9.29497	10.9472	12.5812	16.5717	
		300	60	38	27	23	20	15		
4	0.7815	.7331	3.6608	5.8449	7.2919	8.0120	9.4445	10.8651	14.3549	
		400	80	50	37	31	27	20		
5	0.8773	.6531	3.2619	5.2103	6.5029	7.1467	8.4289	9.7026	12.8424	
		500	100	63	46	39	33	25		
6	0.9637	.5945	2.9700	4.7454	5.9242	6.5118	7.6826	8.8471	11.7244	
		600	120	75	55	46	47	30		
7	1.0430	.5493	2.7446	4.3861	5.4766	6.0204	7.1047	8.1839	10.85496	
		700	140	88	64	54	47	35		
8	1.1167	.5131	2.5637	4.0977	5.1172	5.6257	6.6402	7.6504	10.15397	
		800	160	100	73	62	53	40		
9	1.1858	.4832	2.4145	3.8596	4.8204	5.2998	6.2564	7.2095	9.5736	
		900	180	113	82	69	60	45		
10	1.2511	.45795	2.2886	3.6587	4.5699	5.0247	5.9322	6.8368	9.0824	
		1000	200	125	91	77	67	50		
11	1.3132	.4363	2.1805	3.4861	4.3547	4.7882	5.6536	6.5164	8.6596	
		1100	220	138	100	85	73	55		
12	1.3724	.4175	2.0865	3.3361	4.1675	4.5826	5.4112	6.2375	8.2914	
		1200	240	150	110	92	80	60		
13	1.4292	.4009	2.0037	3.2038	4.0024	4.4012	5.1973	5.9915	7.9662	
		1200	260	163	119	100	87	65		
14	1.4838	.3861	1.92998	3.0862	3.8556	4.2398	5.0071	5.7725	7.6766	
		1300	280	175	128	108	93	70		
15	1.5365	.3729	1.8638	2.9805	3.7237	4.0949	4.8362	5.5758	7.4163	
		1500	300	188	137	116	100	75		
16	1.5875	.3609	1.80399	2.8849	3.6044	3.9638	4.6815	5.3978	7.1805	
		1600	320	200	146	123	107	80		
17	1.6368	.3500	1.7497	2.7982	3.4961	3.8447	4.5411	5.2361	6.9664	
		1700	340	213	155	131	113	85		
18	1.6848	.3401	1.69987	2.7186	3.3968	3.7355	4.4122	5.0877	6.7698	
		1800	360	225	164	139	120	90		
19	1.7315	.3309	1.6541	2.6453	3.3054	3.6350	4.2937	4.9512	6.5889	
		1900	380	238	173	146	127	95		
20	1.7767	.3225	1.61199	2.5781	3.2214	3.5428	4.1848	4.8258	6.4227	
		2000	400	250	182	154	133	100		

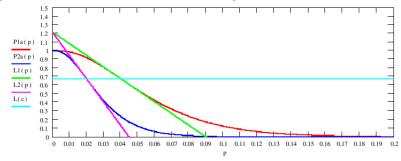
Figure 1: The OC curve, Discriminant, tangent intercept and Tan A of a SSP $(50,\,2)$



1.1 0.9 0.7 P2a (p) 0.6 Р3а (р 0.5 0.4 0.3 0.2 0.1 0.05 0.1 0.15 0.25 0.35

Figure 2: OC curves for the SSP (1) (42, 5), (2) (32, 4) and (3) (53, 6)

Figure 3: OC curves for SSP showing **D** is a constant for fixed c



If no lots are rejected switch to next SSP and so on till maximum c is attained. If at any stage the lot is rejected switch over to previous SSP and inspect 2k lots.

Allow tightening till minimum c is attained.

In example 2.4 possible sampling plans are: (54, 3) (62, 4) (69, 5) (75, 6) (81, 7) (86, 8) (92, 9) and (96, 10). Fix repetitive lot number k = 10.

For example start with (81, 7).

Repeat in 10 lots, if all are good, go to (86, 8).

Continue till, (92, 9), (96, 10) and coninue inspection till a rejection is occurred.

If one of them in 10 lots is not satisfactory at initial inspection level.

At the time of rejection go to (75, 6).

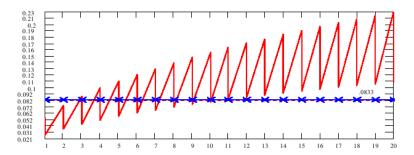
Continue in 20 lots.

If all are good go to (81, 7)

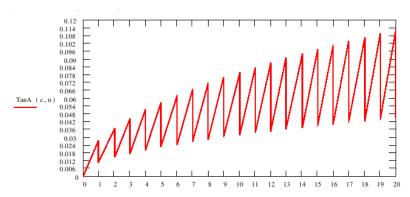
If one is again found bad in these lots switch backward to (69, 5)

Repeat the process till reaching (54, 3) and it is rejected.

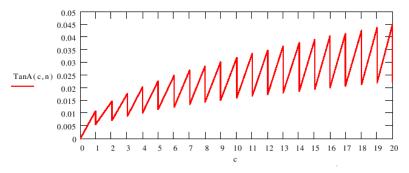
This switching rule will lead to a stochastic process of reaching to optimum sampling plans.



(a) Graphical representation of $\tan A$ for $c=1,2,\dots,20$ and $n=50,\dots,100$ the possible sampling plans with OR=0.0833



(b) Graphical representation of $\tan A$ for $c=1,2,\ldots,20$ and $n=100,\ldots,250$



(c) Graphical representation of $\tan A$ for $c=1,2,\ldots,20$ and $n=250,\ldots,500$

Figure 4:

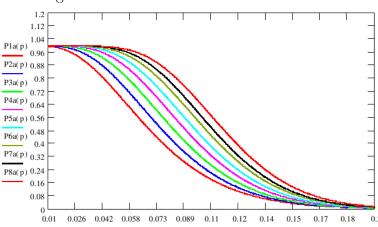


Figure 5: OC curves based on OR=0.0833

References

- [1] Norman Bush. Et al (1953): A method of discrimination for single and double sampling OC curves utilizing tangent of the point of inflection. EN-SAR Report No.P.R. -7, Engineering Agency.
- [2] Mandelson, J. (1962): The Statistician, the Engineer and Sampling plans, Industrial Quality Control, vol.19, pp.12–15.
- [3] . Mayer, P.L. (1956): Some Properties of inflection Point of an OC curve for Single Sampling Plan. Proceedings of 2nd Statistical Engineering Symposium, Published in chemical corps, Engineering Command.
- [4] Muthuraj and Soundararajan, V. (1989): Single Sampling Plan Indexed by point of control and inflection point. Communication in Statistics (Theory and Methods) Vol.14, No.10, 2393–2410.
- [5] Soundararajan. V. (1975): Maximum Allowable Percent Defective (MAPD) Single Sampling Inspections by Attributes Plan. Journal of Quality Technology Vol. 7. No. 4, 173–182.
- [6] Ramkumar, T.B. (1993): A New Design of Attribute Sampling Plan Indexed By AQL, Proceedings, IIIrd Swadeshi Science Congress, November 5–7, Palakkad, India.
- [7] Ramkumar, T.B. (2002): Acceptance Sampling Some Designs and Modifications. Ph.D Thesis University of Calicut, Kerala, India.

ProbStat Forum is an e-journal. For details please visit; http://www.probstat.org.in.